MRR-2

Micro Rain RADAR

User Manual

2011-07-11 Valid for MRR Service Version 6.0.0.2 S / Firmware 6.00

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Table of Contents

1 Safety Precautions

To operate the MRR-2 a mains voltage of 210-240 VAC is needed for the power supply. An improper handling can be dangerous to you. Only competent and instructed persons should work with this system or with parts of it.
The outdoor installation must not be performed in case of an approaching thunderstorm, to avoid a possibly endangering of personnel by lightning.

There are not known any health hazards originating from the emitted electromagnetic radiation of about 50 mW. Nevertheless you should take care that everybody keeps out of the beam above the antenna (parabolic dish) when it is in operation.

All connecting cables, plugs and couplings of the MRR-2 are not interchangeable to prevent any erroneous assembly. This safety precaution is disabled if other types of plugs are installed by the user. Therefore any guarantee explicitly expires and METEK accepts no responsibility for injuries to persons, damage of equipment or other consequences connected with not authorized changing of connectors, cables or other parts of the system.

Depending on regional rules for the use of electromagnetic transmitters frequency permission might be necessary. The operator of the system will be liable for the achievement of such permission. However METEK will be of help with providing adequate information. Copies of the certifications for Germany can be found in chapter 8 of this manual.

2 How to use this manual

The delivered hardware items are described in chapter 4. Make sure that the delivery is complete and free of damage. Consult chapter 5 for setting up the hardware. In chapter 6 the installation and use of the control software is described. The technical specifications are listed in chapter 8.

Chapter 7 contains more detailed information which is not needed for standard operation.

All auxiliary information marked by a grey vertical line on the left margin may be skipped at first reading as it is not needed for standard setting up and operation.

3 Measuring Principle

The Micro Rain Radar MRR-2 retrieves quantitative rain rates, drop size distributions, radar reflectivity, fall velocity of hydro meteors and other rain parameters simultaneously on vertical profiles up to several kilometers above the radar.

It operates with electromagnetic radiation at a frequency of 24,230 GHz with a modulation of 0.5 – 15 MHz according to the height resolution (e.g. 300 m – 10 m). The radiation is transmitted vertically into the atmosphere where a small portion is scattered back to the antenna from rain drops or other forms of precipitation.

Due to the falling velocity of the rain drops antenna there is a frequency deviation between the transmitted and the received signal (Doppler frequency). This frequency is a measure for the falling velocity of the rain drops. Since drops with different diameters have different falling velocities the backscattered signal consists of a distribution of different Doppler frequencies. The spectral analysis of the received signal yields a power spectrum which is spread over a range of frequencies lines corresponding to the Doppler frequencies of the signal.

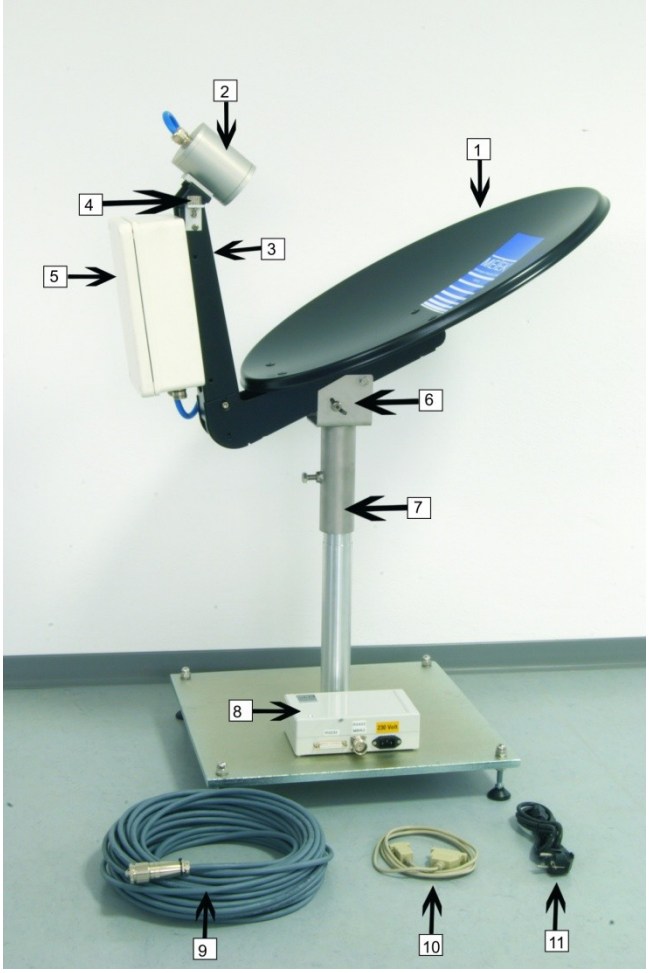
The **R**ADAR **C**ontrol and **P**rocessing **D**evice (RCPD) determines this power spectrum with a high time resolution (10 per second) and sends mean power spectra every 10 s to the connected MRR-PC, where the reflectivity spectrum is calculated considering the calibration parameters of the RADAR module. Using known relations between fall velocity, rain drop size and scattering cross section the drop spectrum (or drop size distribution) is derived. The integration over the entire drop size distribution, considering further correction terms, followed by further averaging over 10 to 3600 seconds, results in rain rate and liquid water content.

The output signal of the RADAR is transmitted continuously (CW mode), a linearly decreasing saw tooth modulation of the transmit signal (FM mode) makes it possible to perform profile measurements with selectable range resolution.

The RADAR antenna is an offset parabolic dish with vertical beam orientation. This antenna design allows rainwater to drain without building ponds. In order to avoid disturbances from snow, which could cover the antenna dish, optional antenna heating is offered.

4 System Description

4.1 Overview



1- Parabolic Dish
2- Transceiver
3- Antenna Arm
4- Bubble Level
5- RCPD
6- Pivot
7- Tube Socket
8- Junction Box
9- Control Cable
10- Serial Cable
11- Power Cable

Figure 1: Components of the System

The MRR-PC, a commercial PC, (not part of delivery) must be ordered separately. The operating system must be Windows® 2000 or XP. (Windows® Vista and Windows 7 are not supported).

4.2 Description of the Components

4.2.1 Parabolic Dish

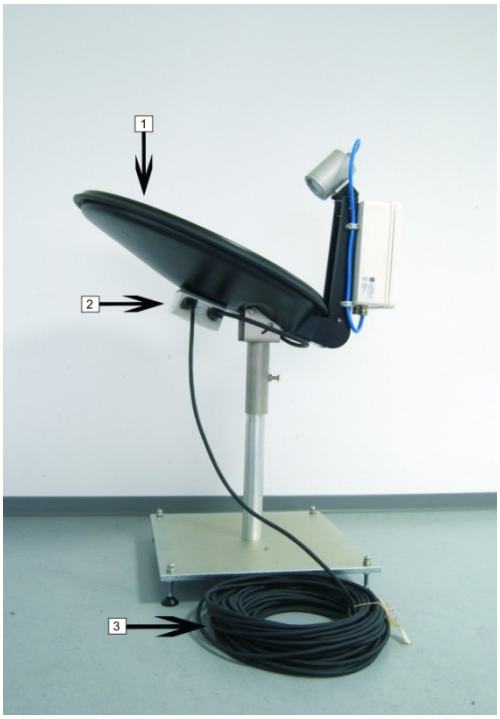
The antenna is used for the transmission of the RADAR signals and the receiving of backscattered signals. It is designed as an offset parabolic dish (see Figure 1). Its largest diameter is 70 cm, the beam width is 2°. Due to the offset-design of the parabolic dish rainwater can drain off.

For antenna mounting the tube socket (see Figure 1) (inner Ø = 49.4 mm) is to be plugged onto a pole with an outer diameter of max. 49 mm. The socket is fastened with an M10 screw.
Connect a ground wire to this screw which serves as a surge protector.

Check the vertical alignment of the antenna with the built in bubble level.

The transmitting and receiving properties of the antenna affect the radar calibration. Therefore the reflector surface should be clean (e.g. free from leaves or wet snow). For the same reason any mechanical deformation of the parabolic dish must be avoided. If nevertheless obvious deformation occurred, the reflector must be replaced.

4.2.2 Antenna Heating (Option)



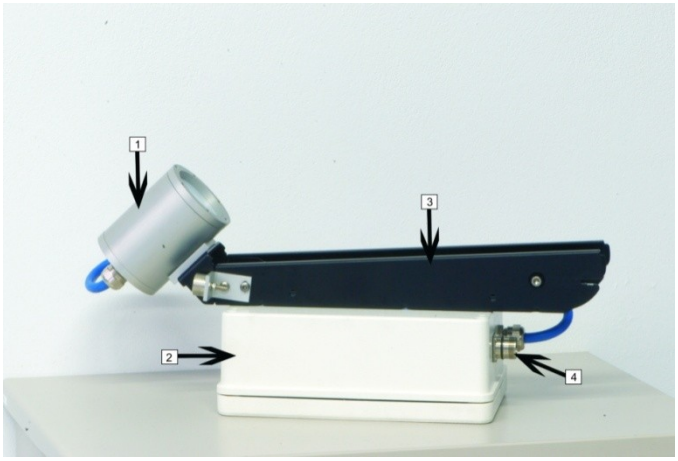
1- Parabolic Dish with Heater
2- Heater Connection Box
3- Heater Power Cable

Figure 2: Antenna Heating

The back side of the reflector is optionally equipped with a heater coil. It is covered and sealed with a molded lid which provides also extra stability for the

reflector. The energy consumption increases with decreasing temperatures and amounts to maximum 500 W. The heating is activated when the temperature falls below a threshold which can be adjusted in the heater-connection box . The heater coil works with 230 VAC voltage supply and needs an extra power cable which is connected to the heater connection box (see Figure 2).

4.2.3 RADAR Control and Processing Device and Transceiver



1- Transceiver
2- RCPD
3- Antenna Arm
4- Connector (Control Cable)

Figure 3: RCPD and Transceiver

The **R**ADAR **C**ontrol and **P**rocessing **D**evice RCPD (see Figure 3) generates the RADAR transmit modulation signal and passes it to the transceiver (see Figure 3). It analyses the backscattered receiver signal, calculates Doppler spectra and transfers average power spectra (referred to as “raw spectra”) to the MRR-PC, where these spectra are interpreted. The RCPD has a water protected IP65 housing, which is fixed to the antenna arm (see Figure 3). At the bottom side of the RCPD is the socket (see Figure 3) for the control cable (see Figure 5). The electronic components inside the housing don’t need any service. As far as possible the RCPD should not be opened by the user.

4.2.4 Junction Box / Power Supply

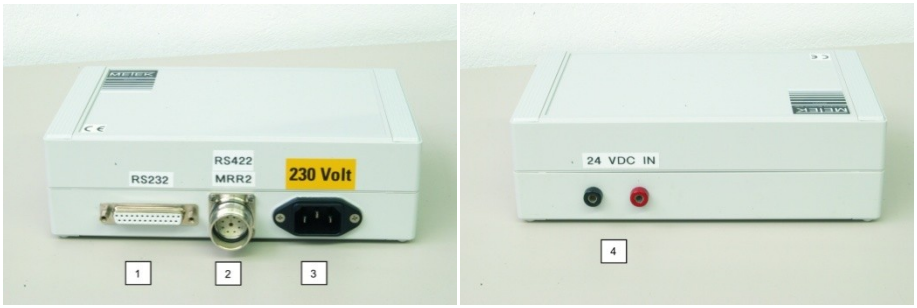


Figure 4: Junction Box, Left: Front Side, Right: Back Side

The junction box is used to pass through the communication between the PC and the RCPD. For this purpose it has a 25-pin D-sub-miniature socket for the serial cable (see Figure 5) to the MRR-PC and a flanged socket for the control cable (see Figure 5) to the RCPD.

The power supply for the RCPD and Transceiver is also integrated in the junction box. An IEC connector for the mains supply of 230 VAC is on the front side of the case. On the back side are two sockets for banana plugs for the connection of an alternative external DC power supply (see Figure 4). The power supply (24 VDC) for the RCPD and Transceiver is also passed through the control cable (see Figure 5).

All MRR systems produced in 2011 ff. are equipped with an RS422 Interface: The communication between RCPD and Junction Box is on RS422 level. In the Junction Box the signals are converted to RS232 level.

The communication between junction box and PC is on RS232 level.

MRR systems prior to 2011 use only RS232 level for communication, there is no RS422/RS232 converter in the junction box.

Note: The junction box is not appropriate for outdoor operation.

4.2.5 Control Cable and Serial Cable

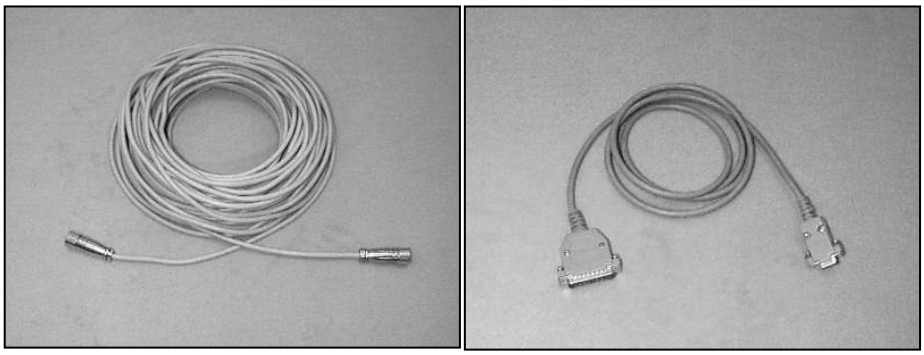


Figure 5: Control Cable (left) and Serial Cable (right)

The control cable connects the RCPD with the junction box.
The control cable has a length of 25 m, on both ends are screwed plugs (male and female respectively). They must be screwed onto the matching plugs at the junction box (cable has pins) and at the RCPD (cable has sockets).

The serial cable (RS232) connects the Junction Box with the PC.
The maximum length of the serial cable is 2 m, a serial cable with a 9-pin (female) and a 25-pin (male) plug and a length of 1.5 m is delivered. This cable is not appropriate for outdoor applications.

4.2.6 MRR-PC

A personal computer (PC) with the operating system Windows® 2000 or XP serves for setting the operation parameters and data evaluation of the MRR. (Windows® Vista and Windows® 7 are not supported so far). The PC must have at least one serial port which will be configured by the control program as follows:

57600 baud,
8 data bits, no parity,
Software Handshake (XON/XOFF)

Pinning (D-Sub-25-socket at the junction box) :

Pin 2	RD	*receive data*
Pin 3	TD	*transmit data*
Pin 4	RTS	*request to send*
Pin 5	CTS	*clear to send*
Pin 6	DSR	*data set ready*
Pin 7	GND	*ground*
Pin 8	CD	*carrier detect*
Pin 20	DTR	*data terminal ready*
Pin 22	RI	*ring indicator*

The control program which is needed to operate the MRR-2 is part of delivery. Its installation and operation is described in section 6 *Control Program* page 19.

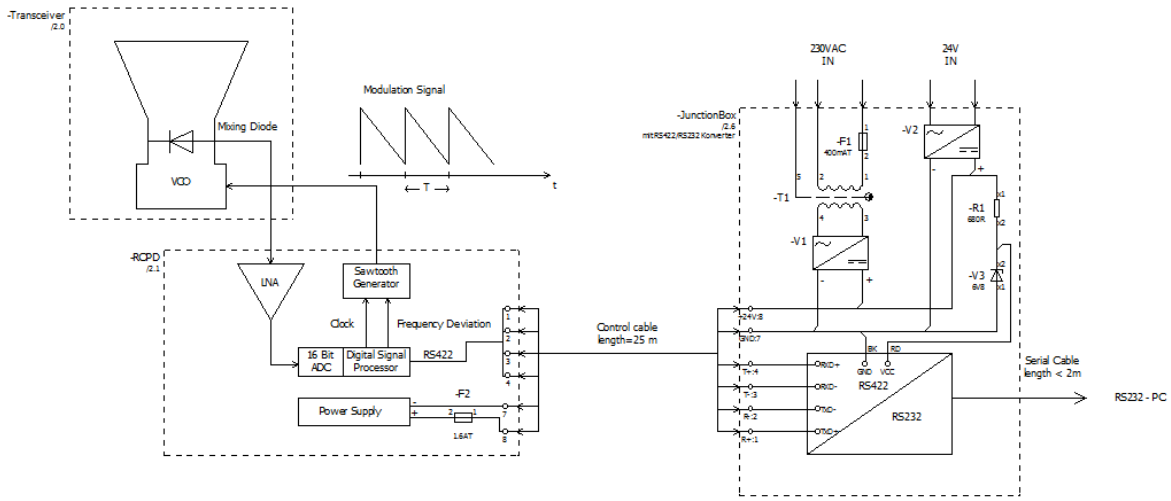


Figure 6: MRR block diagram

5 Hardware Installation

5.1 General Provisions

- Before you start the system, all cable connections must be set up.
- Only the antenna unit including RCPD, Transceiver and control cable (see Figure 1) are designed for outdoor operation. All other components, e.g. the junction box and PC, must be installed in a weather
  protected environment with temperatures within 5 - 40°C.
- The electronic cases may be opened only in dry environment. Especially in outdoor area you risk damage by moisture.
- If cables are laid on free field, a cable conduit is recommended.
- All cable connections should be protected by strain-reliefs.
- Use only the original connectors. Guarantee is void, if other connectors are installed.

5.2 Site Conditions

Before actual installation the site must be checked for its suitability for rain measurements.

There must be free view of at least 10° zenith angle over the radar.

Nearby transmitters (base stations of mobile phones, broadcast towers, radars) can cause interference although they operate nominally at different frequency bands. If such neighborhood is necessary, a simple metallic screen or larger object (container) obscuring the direct line of sight to the interfering source can help.

The vicinity of electric machines (e.g. drive of elevators) should be avoided, since they can create interfering signals which are difficult to screen.

If measurements at very low heights are planned, (with appropriate settings the MRR-2 allows measurements from a minimum height of 20 m above ground) take care that the wind field in this level is not disturbed by nearby buildings, trees, masts etc., because strong turbulence could falsify the data.

In contrast with in-situ rain sensors the exposure of the antenna to the free wind field is not detrimental but favorable.

Figure 7 shows various examples of MRR installations: On ground, on top of containers and on top of buildings.

Figure 7: Examples of MRR installations

5.3 Installation Procedure

Preparations:
A fixed vertical pole (Ø max. 49 mm, length min. 30 cm) is required for attaching the antenna. Operating of the MRR-2 requires a 230 VAC mains supply, with a fuse protection of 8 A (slow) minimum. To prevent disturbance of the device by variations or breaks of the power supply we recommend the use of a no-break power supply (UPS).

Required Tools: A wrench with 17 mm opening.

Installation Steps:

1. Install the MRR-PC according to the documents of the manufacturer.
2. Plug the tube socket (see Figure 1) of the RADAR antenna over the attachment pole and clamp it with the M10 fixing bolt.
3. Check the vertical alignment of the antenna with the built in bubble level (Figure 8).

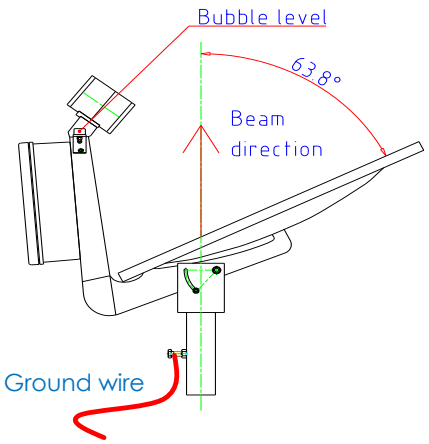


Figure 8: Vertical alignment of the radar beam

4. Attach a ground wire to the fixing bolt for lightning protection after mounting of the antenna (Figure 8).
5. Connect the control cable between RCPD and Junction Box. Ensure that the nut cap is tightly screwed, if the black o-ring is visible the connection will not be waterproof (see Figure 9).

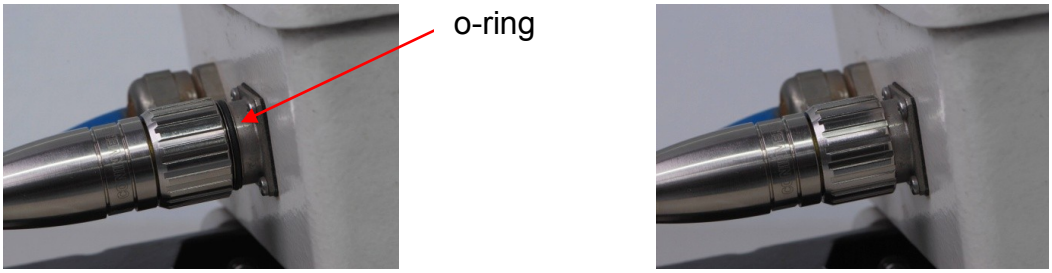


Figure 9: Control cable connector

6. Connect serial cable (Figure 5) to the serial interface of the MRR-PC, which was selected in the operating system for the connection of the MRR-2. If this serial port is unknown, it can be looked up in the administration of the "services" in the operating system of the computer and it can be changed accordingly there. See also installation of the control program chapter 6.

7. Connect power cable of the Junction Box to the mains voltage of 230 VAC.
8. Check the power supply of the Transceiver: If the cabling is Ok a green LED in the Transceiver indicates the correct supply.

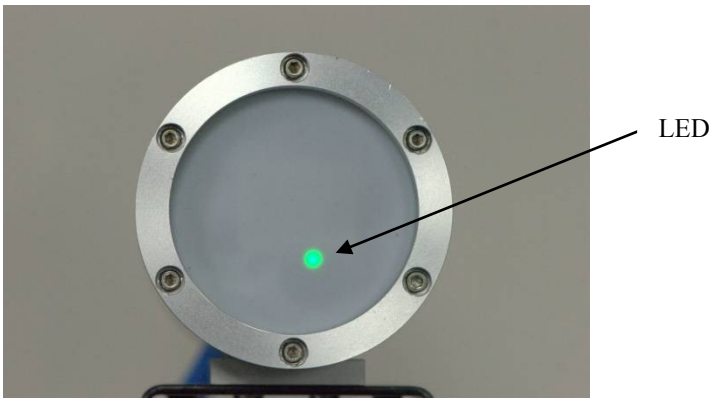


Figure 10: Transceiver with LED

9. Establish the communication between the control program „MRR-2 Control" and the RCPD-firmware.
10. Check the correct data transmission and recording.

6 Control Program

If you use your own PC for controlling the MRR-2 the MRR program is delivered on a CD-ROM and must be installed according chapter 6.1.

If the PC was configured and delivered by METEK (optional) chapter 6.1 may be skipped.

6.1 Installation

The software can be installed on a PC with Windows® 2000 or Windows® XP (Windows® Vista and Windows® 7 are not supported).

For installing the Control Program:

- Insert the CD-ROM.
- Login as administrator.
- Open the program group `my computer` (icon on the desktop).
- Open the folder for the CD-ROM device.
- Change to the folder `METEK`.
- Start the program `MRRSetup_V6002.exe`

The setup program will start with the welcome screen, click the next button to proceed with the installation. The next screen is the destination folder selection (default: C:\Program Files\METEK Software\MRR), normally no changes are needed, please confirm with “Next”.

Figure 11: Welcome Screen

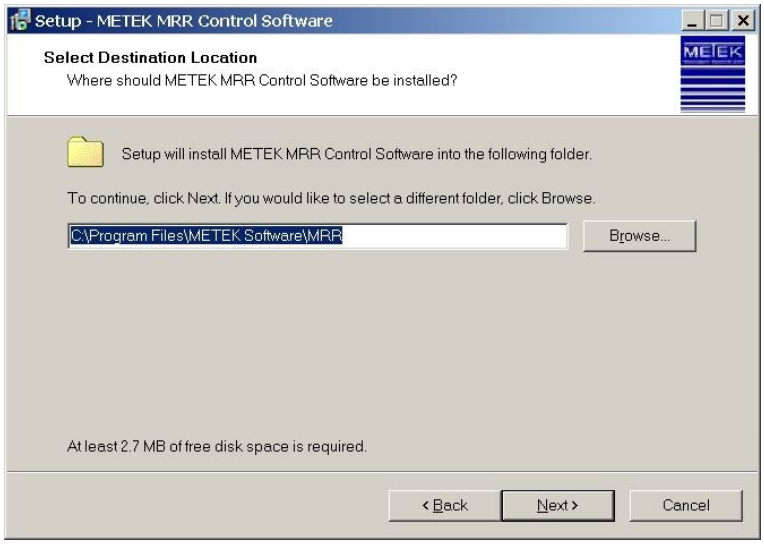


Figure 12: Destination Folder

The next screen is the selection of the data folder (Figure 13), the default value for the data folder is
“D:\Documents and Settings\All Users\Documents\MRR Data”
(default value depends on the windows version), please change this value according to your preferences and confirm with “Next”.

In a next step the communication port (Figure 14) is selected: the list of the serial ports shows all available serial ports on your PC, please change this value to your preferences and confirm with “Next”.

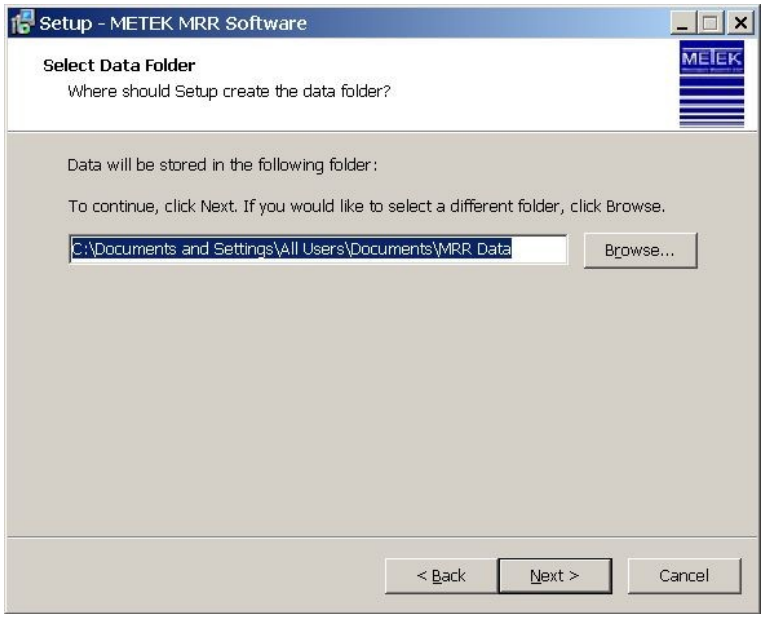


Figure 13: Data Folder

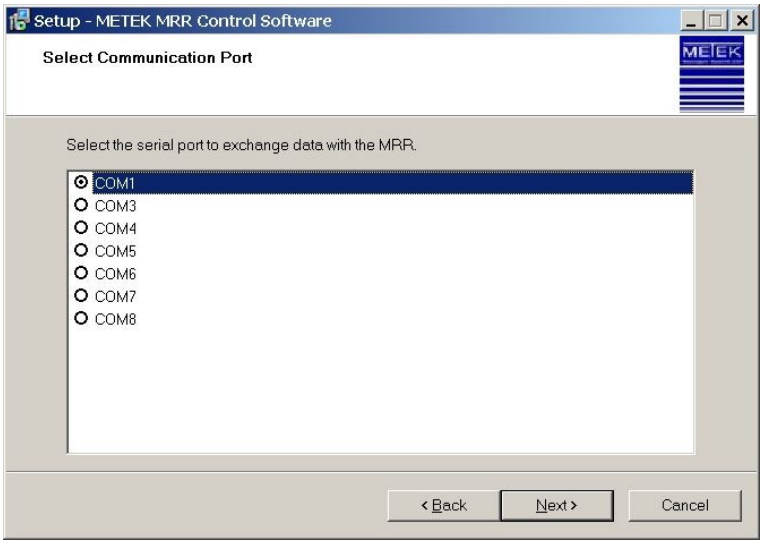


Figure 14: Communication Port

In the next step all selected values are shown (Figure 15)in a list and you can start the installation by pressing “Install”, if you want to make changes before your installation you can go back and change the settings.

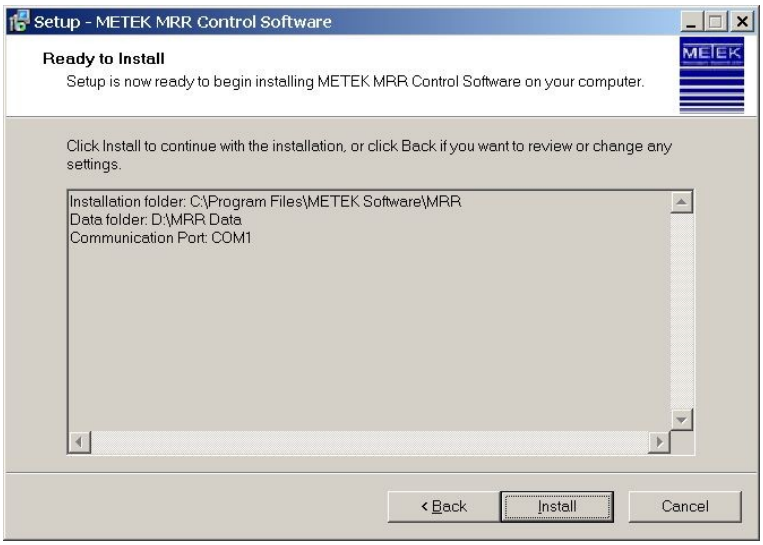


Figure 15: Install

If you press install, the installation starts and will display a message box:

Figure 16: Service installed

In a last step the finish screen disappears, with “Finish” you can terminate the setup program.

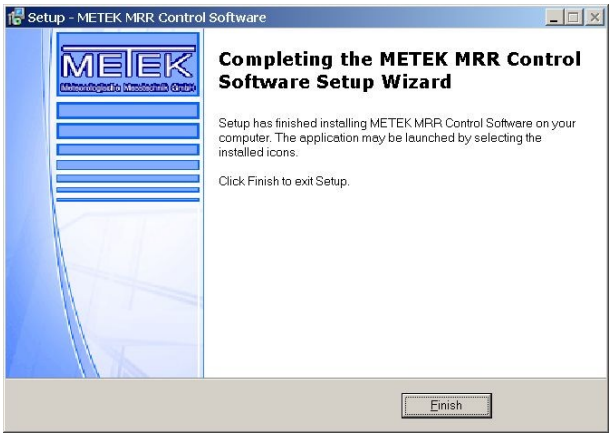


Figure 17: Finish

Note: The data flow rate from the MRR to the PC requires that the PC response time does not exceed certain limits. If the PC was configured and delivered by METEK (optional), meeting of this request is warranted.

Any modern PC with medium performance is basically sufficient to run the MRR Control Program, if there are not too many other tasks running simultaneously. Particularly virus scanning programs may slow down the PC below the minimum possible value. In that case the data records are corrupted.

Please check the integrity of recorded data by visual inspection and reduce the processor load if necessary.

6.2 Using the Control Program

After login to the operating system press the “Start” Button and open the menue “METEK Software” , then selct “MRR” and then select “MRR Control”.
The following dialogue window appears (The screenshots in this manual were taken from a Windows® 2000 system.):

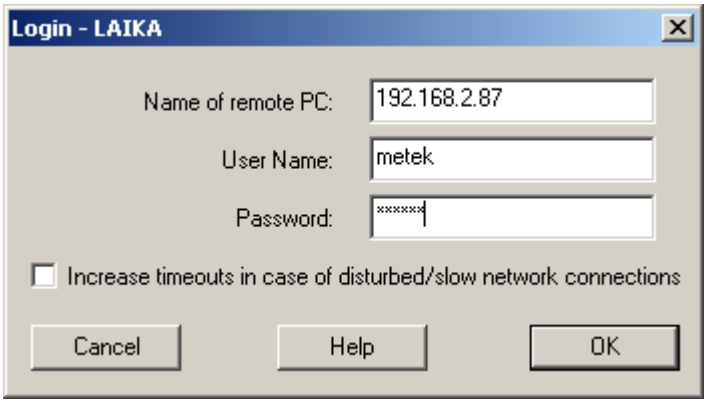


Figure 18: Login Screen

If the MRR-PC you are sitting at is the PC which is directly connected to the MRR-2 leave the entry at ***Name of the Remote PC*** empty (or type a period or the name of the local PC). If you are sitting at another PC, enter the name of that PC to which the MRR-2 is connected directly and where the communication service (`MrrCtrl.exe`) was started.
The User Name is generated automatically and the Password is usually not needed (see below for exceptions).

The ***Password*** entry field is useful if the remote computer is a member of another Windows domain, because in this case a connection can be built up only if a user name and the matching password is given. The user name is set automatically (see the header of the dialog window).
The network connection to the remote computer usually is a LAN- or a RAS connection. RAS connections using the public telephone net are mostly not very efficient, especially connections with mobile phone radio nets. Considering that, the login dialog provides the use of time-out-values which are adjusted to the maximum delay times for the responses from the remote PC. Using a direct LAN or a local login, this feature is not needed.
If the program was started by a command line input, the information concerning the login window can be handed over as a parameter. Example:

```
C:\METEK\MrrCtrl hostname secret /t
```

This entry would try to build a connection to a computer with the name `\\hostname`. The password is `secret`, the time-out-values are set for slow WAN connections (`/t`). The parameter `/t` is optional, the computer name and the password however must be given always. This is also valid for local logins (the password will not be checked).
If the connection to the communication service could be built up, the entire status of the MRR-2 is read out first. This can take some seconds, on RAS connections even some minutes.

6.2.1 Main Menu

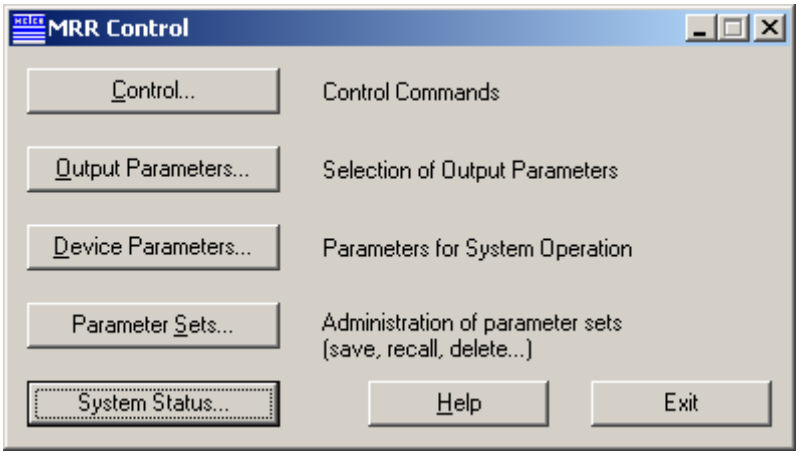


Figure 19: Main Menu

The main menu shows buttons for the menus

Control	chapter 6.2.2 on page 24
Output Parameters	chapter 6.2.3 on page 26
Device Parameters	chapter 6.2.4 on page 28
Parameter Sets	chapter 6.2.5 on page 30
System Status	chapter 6.2.6 on page 32

You can leave the program with the ***Exit*** button.
The ***Help*** button provides a Windows conforming help text.

6.2.2 Control Commands Menu

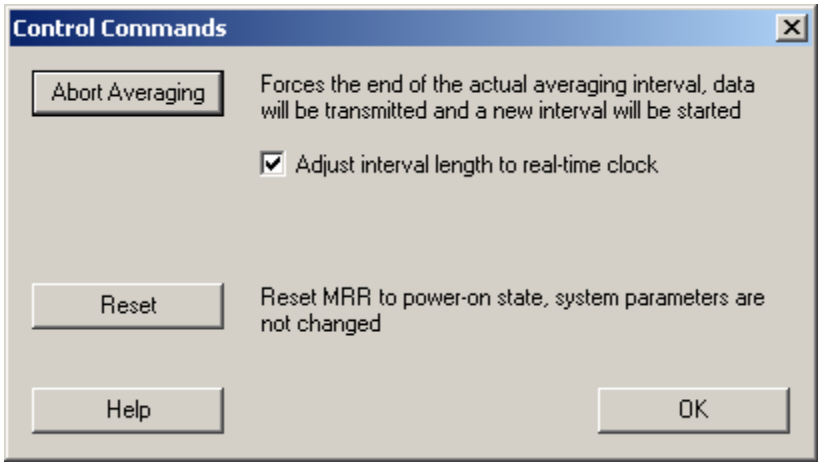


Figure 20: Control Commands

Abort Averaging

The current averaging interval is stopped. Data, collected since the begin of the averaging interval, are processed and a new averaging interval is started regardless of elapsed averaging time.

Adjust interval length to real time clock

This checkbox activates the synchronization of measuring intervals to the actual time of day. This means every output of averaged data will occur at 'round' times. Example:
If the measuring time has been set to 600 seconds, output will be generated at every full 10 min.

Reset

Pressing this button will perform a reset of the RCPD firmware. There is no influence on the MRR-2 parameters. It has the same effect as an interruption of the power supply.

6.2.3 Output Parameters Menu

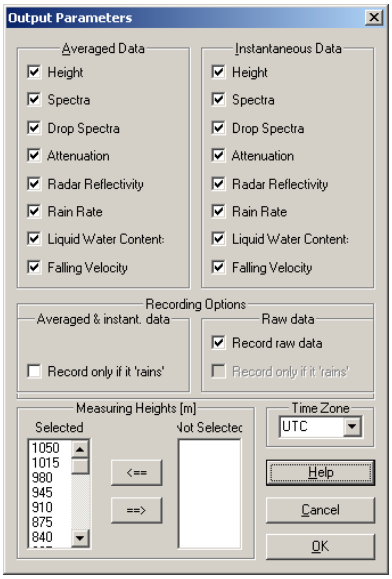


Figure 21: Output Parameters

The two upper panels shown in **Fehler! Verweisquelle konnte nicht efunden werden.** contain check boxes for configuring selections of *averaged data* and *processed data* separately for recording. *Processed data* are calculated on the basis of <u>one</u> raw spectrum[1]. *Averaged Data are processed* on the basis of an average of multiple raw spectra, depending on the selected averaging time. The selectable variables are described in the table below.

Selection of	**causes the recording of**
Height[2]	Measuring height above ground
Spectra	Spectral volume reflectivity
Drop Spectra	Drop diameter and number of drops per volume and diameter
Attenuation	Two way path integrated attenuation
Radar Reflectivity	Radar reflectivity factor and attenuated radar reflectivity factor
Rain Rate	Vertical volume flux of liquid water per unit area
Liquid Water Content	Mass of liquid water per volume
Falling Velocity	Doppler velocity (1. moment of the spectrum)

[1] raw spectra and the processed data represent already averages over 10 seconds, these averages are calculated out of approx. 78 instantaneous spectra.
[2] The output variable *Height* should always be selected, as this facilitates further processing of recorded data.

Recording Options

Raw Spectra
By checking “Record raw spectra” the raw spectra including metadata are written in addition to other selected data to a separate log-file. The path name of these files is defined by the parameters RawSpectraFile , RawSpectraPath.

Conditional recording
By checking “Record only if it rains” data are only recorded, if the evaluation software detects precipitation during the measuring (averaging) interval. This condition can be activated separately for averaged/processed data and raw spectra respectively.

Measuring Height(s)
A subset of measuring heights can be selected for recording. This subset is used for both kinds of data output, processed and averaged data. The selection of measuring heights for output is done with two lists containing the selected and unselected height steps. To move items (sets of height steps) between the lists they must be marked in the source list. The movement will be performed when the arrow button pointing to the other target list is pressed.
(The *height resolution* (step-width) can be adjusted with the device parameters menu (see chapter 6.2.4 on page 28)).

Time Zone
The time zone can be selected which is used for the time stamps of the recorded data.

All changes in the Output Parameters Menu become effective by clicking the “Ok” button. Then the corresponding commands are transmitted to the RCPD firmware. Clicking the “Cancel” button cancels all changes.

6.2.4 Device Parameters Menu

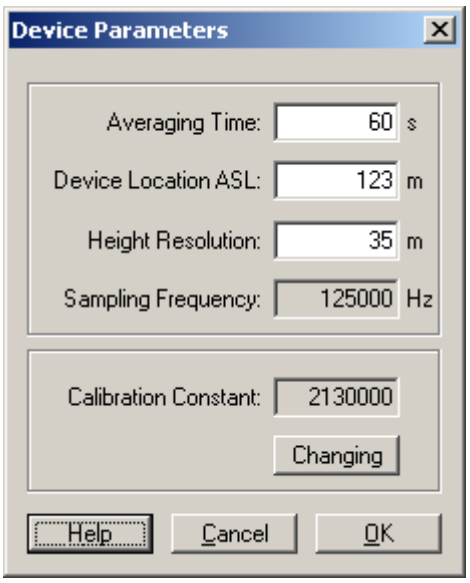


Figure 22: Operation Parameters

Averaging Time

Here you define the averaging time for the *averaged data*.
The adjustable range is 10 .. 3600 s.

After each averaging time, an *averaged data* set is generated and recorded and a new averaging interval starts. Processed data are generated and recorded independently in 10 s time intervals within each averaging interval.

Device Location ASL

Enter the height of the MRR-2 location above sea level. The adjustable range is 0 ... 9999 m. This parameter is used for the density correction of the fall speed versus drop size relation.

Height Resolution

Enter the desired distance between adjacent measuring heights (step width).
The adjustable range is 10 – 1000 m. Typical values are 30 – 100 m.
The measuring heights are integer multiples of the height resolution. The maximum number of height steps is 31.

Sampling Frequency

Number of samples per second of the analogue input signal of the MRR-2. This parameter can't be changed by the user.

Calibration Constant

This constant is needed for converting the engineering units of the receiver signal (raw spectra) into physical units (processed and averaged data). See Physical Basis for details. The calibration constant is factory set. Nevertheless it can be changed by the experienced user. Before a new calibration constant can be entered the "changing" button must be pressed. It should be only done, if there is clear evidence for a miss-calibration of the MRR. This can be inferred for example from rain rates measured with the MRR (R_{MRR}) and a rain gauge (R_{RG}) respectively. If C_{old} is the old calibration constant, the new calibration constant C_{new} can be calculated according

$$C_{new} = C_{old} \frac{R_{RG}}{R_{MRR}}$$

It should be kept in mind that comparisons of rain rates measured aloft with the MRR and a rain gauge are not straightforward due to the strong inhomogeneity of rain. MRR data should be taken from range gates not below the 3rd range gate, because approximations in the radar equation cause larger biases at lower range gates. On the other hand the measuring height should not exceed 200 m in order to keep attenuation effects small (they are only eliminated in case of correct calibration) and to keep the correlation with surface precipitation at a useful level. Further make sure that the MRR rain retrieval is not affected by the ice phase or melting processes. Strong winds should also be avoided since rain gauges tend to unreliable under such conditions.

OK

All changes in the Device Parameters Menu become effective by clicking the "OK" button. Then the corresponding commands are transmitted to the RCPD firmware. Clicking the "Cancel" button cancels all changes.

6.2.5 Parameter Storage

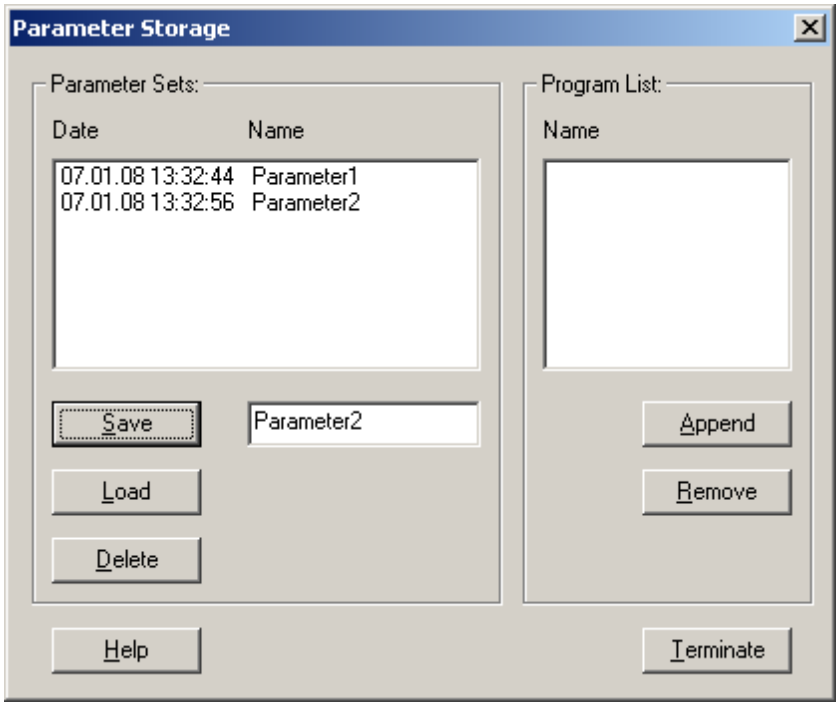


Figure 23: Parameter Storage

Parameter Sets

The parameter memory of the MRR-2 is used for convenient saving and loading of complete parameter settings.

A parameter set consists of
- the device parameters (except calibration constant) and
- the selected output parameters

Saving a parameter set:
- Type a name in the field right of the ***Save***-button or select a name of the Parameter Sets list.
- Click the ***Save***-button.

Loading a parameter set:
- Type a name of the Parameter Sets list in the field right of the ***Save***-button or select a name of the Parameter Sets list.
- Click the ***Load***-button.

Deleting a parameter set:

- Type a name of the Parameter Sets list in the field right of the ***Save***-button or select a name of the Parameter Sets list.
- Click the ***Delete***-button.

Program List

Previously defined parameter sets can be added to a program list. All sets, which are included in this list, will be processed successively. This means every time the averaging interval has finished, the next entry will be loaded from the list. After reaching the end of this list, the program starts over with the first entry.

Creating a Program List

- Select a parameter set in the Parameter Sets list
- Click the ***Append*** button. The parameter set is inserted in the empty Program List or added to the end of the non-empty Program List.

As soon as the Program List is not empty, it becomes active.

Removing entries from the Program List

- Select the entry from the Program List
- Click the ***Remove***-button

Note:

1. Parameter sets, which appear in the Program List can neither be changed nor deleted.
2. The same parameter set name may appear at several places in the Parameter List.

6.2.6 Status messages

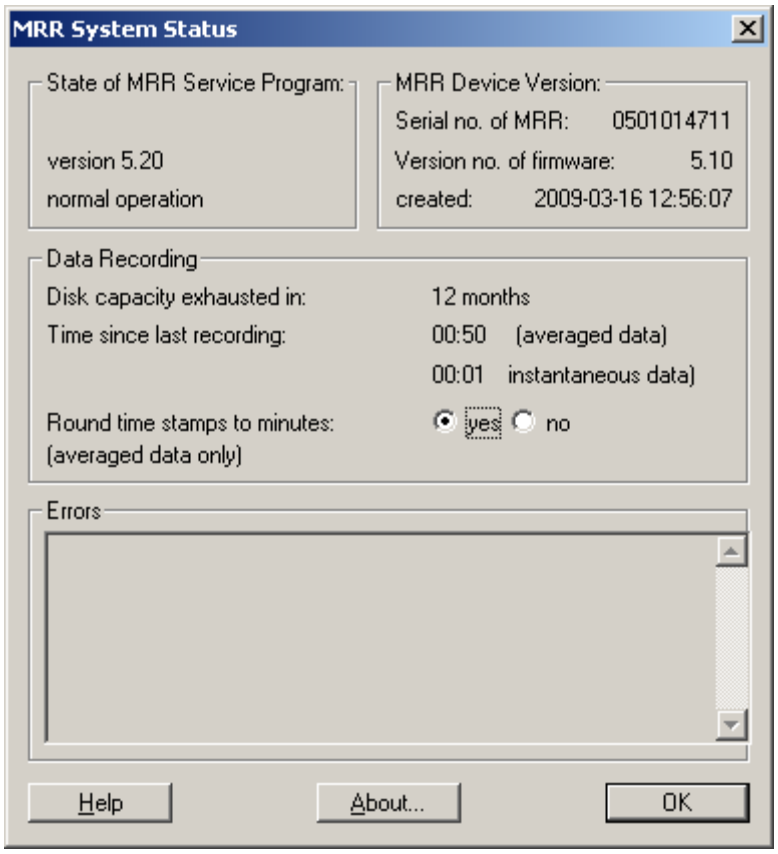


Figure 24: System Status

Sub-Panel: "State of the MRR Service Program"

The version number of the MRR-Service is shown.

The operation state is shown:

- *normal operation*
  No problems occurred.
- *erroneous operation*
  It should appear if the COM Port couldn't be opened or the communication channel between Control Program and MRR-Service couldn't be established. The Control Program will terminate in both cases before this message can be displayed.

Sub-Panel: "MRR Device Version"

The serial number, the firmware version number and the firmware creation date of the connected MRR are shown.

Sub-Panel: “Data Recording”

- *Disk capacity exhausted in*
  The remaining time for data recording is shown. The calculation is based on the average sizes of the last received measuring protocol and the actual free disk space (Initially **???** appears until the first data set is stored).

- *Time since last recording*
  The time elapsed, since the last averaged and processed data sets were written to disk, is shown (Initially **???** appears until the first data set is stored).

- *Round time stamps to minutes*
  Time stamps are rounded to integer values. This can be useful under thefollowing condition: If the "Adjust interval length to real time clock" (see chapter 6.2.2 **Control Commands Menu**) was selected, the time stamps should be integer multiples of 10 seconds, minutes or ten minutes. Nevertheless small deviations from these integers may occur due to variable processing time. If this is disturbing for subsequent data analysis programs, the recorded time stamps can be rounded. The selection *yes* or *no* is activated by pressing the *ok* button.

Sub-Panel “Errors”

This panel shows a list of errors which occurred during the measuring operation. Errors which occurred before the control program was started can be retrieved from the Windows® 2000 or Windows® XP event log.

About Button

If you press the “About” Button version information about the control program appear.

6.3 Processed and averaged data

6.3.1 Format description

Processed and averaged data are archived in two separate directory structures (see chapter 7.1.2 Data Recording on page 46). Optional recording of so called raw spectra, which represent the unprocessed measuring data of the MRR-2, is possible.

The data format is human readable ASCII text. Each data set consists of one line. The order of the data lines and the used identifiers are listed below:

Identifier	Meaning	Unit	Remark
MRR	*Header Line*	n.A.	
H	*Height*	m	
TF	*Transfer Function*	dimensionless	
F*nn*	*Spectral Reflectivities*	dB	$10 \cdot \log \eta_{nn}$ with η_{nn} in m^{-1} *nn* from min(*h*) to max(*h*) [3]
D*nn*	*Drop Size*	mm	Center of size class
N*nn*	*Spectral Drop Densities*	$m^{-3}mm^{-1}$	$N(D_{nn})$ [4]
PIA	*Path Integrated Attenuation*	dB	
Z	*Radar Reflectivity*	dBZ	$10\log\left(\sum_{nn=\min(h)}^{nn=\max(h)} N(D_{nn})D_{nn}^{6}\right)$ *nn* from min(*h*) to max(*h*)
z	*Attenuated Radar Reflectivity*	dBZ	Z-PIA
RR	*Rain Rate*	$mm\ h^{-1}$	
LWC	*Liquid Water Contents*	$g\ m^{-3}$	
W	*Fall Velocity*	$m\ s^{-1}$	

The measured data are displayed in lines following the header. For each measured variable there is one line starting with a 3-character identifier of the variable. Each line represents a profile of this variable, i.e. a function versus height. Each data entry is 7 characters wide. Height is running from left to right

[3] *See MRR-Physical Basics for details*.
[4] *See MRR-Physical Basics for details*.

in increments according to the chosen height resolution of the MRR. Invalid or not calculable values are coded as 7 consecutive space characters.

MRR – Header Line

The header line marks the beginning of a data set. It starts with the identifying string ”MRR“, a space character and a date/time stamp. The date/time stamp consists of 12 digits (format *YYMMDDhhmmss*), a single space character and the name of the time zone. This name starts with the string „UTC“ and is optionally followed by an offset value (format ±*hh* or ±*hhss*). The time stamp is generated from the PC time. Then several parameters follow:

“AVE” **Ave**raging time in seconds (“AVE”),

“STP” height resolution in meters (“STP”),

“ASL” height of the ground level **A**bove **S**ea **L**evel in meters (“ASL”),

“SMP” **s**a**mp**ling rate of the RADAR signal in the time domain (unit: Hz),

“SVS” version number of the MRR Service (service version number),

“DVS” version number of the MRR firmware (device version),

“DSN” serial number of the MRR (device serial number)

“CC” calibration constant

“MDQ” data quality parameter consisting of the identifying string. This number is the percentage of valid spectra collected during the averaging interval. Spectra can be invalid due to saturation of the AD converter – caused either by extreme precipitation or by some interference.

“TYP” indentifier for the kind of data: AVE-averaged data, PRO-processed data or RAW-raw spectra

Each of the parameters in the header line starts with a delimiting space character, the 3-character identifier as shown above in the parentheses and a field of 6 characters for the numerical value (except of the serial number, which can consist of up to 10 numeric characters between 0 and 9).

Example (Each entry of the header line is shown in a separate line of the table) :

MRR␣110124040200␣UTC	The header line dates from January 24th, 2011, 4:02 AM, timezone 'UTC'.
AVE␣␣␣60	Averaging time is 60 seconds.
STP␣␣␣35	Height resolution is 35 meters.
ASL␣␣147	The radar is sited 147 meters above sea level.
SMP␣125e3	Sampling rate is 125,000 Hz.
SVS␣6.0.0.1	Version number of the MRR Service is 6.0.0.1
DVS␣6.00	Version number of the MRR firmware is 6.00.
DSN␣0502082121	Serial number of the MRR is 050208121.
CC␣2066000	Calibration constant is 2066000.
MDQ␣100	Percentage of valid spectra is 100
TYP␣AVE	data are averaged data

H - Height

Argument of the following data profiles corresponding to the settings described in chapter 6.2.3*,* page 26, and chapter 6.2.4, page 28. The units are meters above the radar system.

TF - Transfer Function

To each height step a value of the Transfer Function is assigned by which raw spectra are divided.

Fnn with nn from 0 to 63 - FFT Spectra

Each line represents a profile of spectral reflectivity corresponding to the spectral bin *nn*. As **Fnn** is corrected for the receiver noise floor negative values can occur, if the signal to noise ratio is low. These entries cannot be presented in the logarithmic domain and are replaced by space characters.

Dnn with nn from min(h) to max(h) - Drop Sizes

The drop size is described by the diameter of an equivolumic sphere. The spectral bins of drop numbers are of variable width in the size domain (in contrast with spectral bins in the frequency- and velocity-domain). In addition, the widths of the size bins are slightly height dependent. Therefore the

assignment of frequency-bin-index nn to diameter D is listed explicitly for each bin and height. The center of each size class is displayed.

Nnn with nn from min(h) to max(h) - Spectral Drop Densities

With the knowledge of the frequency of the Doppler-shift the calculation of the corresponding drop fall velocity is possible (equation 1.4.3.2 in MRR Physical Basics). Thus each FFT-line stands for a drop size interval. Chapter 2 in the Physical Basics shows how to derive from the received spectral power the number of drops for this drop size class, and finally – by division through the variable class width – the spectral drop densities.
Only a sub-set of all 64 spectral bins is considered for the calculation. The lower (min(h)) and upper limit (max(h)) depends on the height as described in MRR Physical Basics (Fig. 7).
In case of negative values of Fnn negative drop number densities are calculated. Although they have no physical meaning they are retained in order to avoid statistical biases.

PIA - Path Integrated Attenuation [1)]

The two-way Path integrated attenuation by rain drops is calculated as described in chapter 3.2 “MRR-Physical Basis” and is used for correction of Nnn, Z, RR and LWC.

z - Attenuated Radar Reflectivity[2)]

z is the radar reflectivity factor (see chapter 3.1 MRR-Physical Basics) without attenuation correction

Z - Radar Reflectivity[2)]

Z is the radar reflectivity factor (see chapter 3.1 MRR-Physical Basics)

RR - Rain Rate[2)]

RR is the rain rate (see chapter 3.3 MRR-Physical Basics)

LWC - Liquid Water Content[2)]

LWC is the liquid water content (see equation 3.2.1 MRR-Physical Basics)

[2)] *In case of low signal to noise ratio negative values can occur. Although they have no physical meaning they are retained in order to avoid statistical biases*.

W - Fall Velocity

W is the characteristic falling velocity.
(First Moment of the Doppler spectrum, see chapter 3.4 MRR-Physical Basics).
The width of velocity-bins can be derived from the maximum number of height steps, the sampling rate (as shown in the header line) and the wave length of the RADAR signal. 32 height steps and 64 lines per step are calculated. For a sampling frequency of 125 kHz and a transmit frequency of 24.23 GHz, the resolution of the fall velocity can be calculated as:

$$\frac{125\,\mathrm{kHz}}{2}\,\frac{1}{32\cdot 64}\,\frac{299700\ \mathrm{km/s}}{2\cdot 24.23\,\mathrm{GHz}} = 0{,}1887\ \mathrm{m/s}$$

6.3.2 Processed and averaged data example

Processed and **averaged data** files have the same structure including the header lines. Only the data type identifier “TYP PRO” resp. “TYP AVE” at the end of the header line are different.

```
MRR 110124085700 UTC AVE    60 STP    10 ASL     0 SMP 125e3 SVS 6.0.0.1 DVS 6.00 DSN
0200708021 CC 2079868 MDQ 100 TYP AVE
H       35     70    105   …       1015   1050   1085
TF  0.0115 0.0420 0.0999   …     0.6890 0.6406 0.4225
F00 -65.29 -74.53 -82.05   …     -82.32 -87.28 -83.34
F01 -66.94 -76.22 -84.02   …     -80.55 -85.48 -84.48
F02 -72.75 -81.78 -88.82   …     -79.20 -84.64 -84.43
F03 -82.02 -88.54 -91.72   …     -79.97 -85.73 -84.42
F04 -88.10 -89.28 -91.25   …     -81.30 -87.44 -89.43
F05 -87.30 -88.16 -90.08   …     -81.83 -92.29
F06 -86.28 -87.67 -89.08   …     -81.55 -91.37
F07 -85.61 -87.55 -87.62   …     -80.73 -86.27 -90.26
F08 -85.09 -86.74 -85.56   …     -80.90 -83.80 -86.63
F09 -83.82 -85.29 -84.11   …     -83.05 -86.41 -87.24
F10 -81.72 -83.85 -83.09   …     -87.40        -86.95
F11 -80.23 -82.49 -81.94   …     -84.87-101.37 -83.71
F12 -79.40 -81.17 -80.57   …     -81.59 -86.14 -78.92
F13 -78.57 -79.85 -79.34   …     -80.78 -81.78 -74.26
F14 -77.86 -78.66 -78.36   …     -79.66 -76.73 -69.46
F15 -77.06 -77.59 -77.41   …     -77.10 -71.53 -65.20
F16 -75.62 -76.37 -76.39   …     -73.66 -66.92 -61.51
F17 -74.28 -75.27 -75.46   …     -70.42 -63.54 -58.70
F18 -73.30 -74.28 -74.44   …     -67.66 -61.18 -56.98
F19 -72.19 -73.25 -73.11   …     -65.18 -59.40 -56.03
F20 -71.06 -71.94 -71.65   …     -62.92 -57.99 -55.55
F21 -70.02 -70.51 -70.34   …     -61.00 -56.68 -55.21
F22 -68.79 -69.29 -69.18   …     -59.54 -55.98 -55.17
F23 -67.82 -68.28 -67.92   …     -58.11 -55.69 -55.47
F24 -67.15 -67.36 -66.44   …     -56.56 -55.26 -55.78
F25 -66.05 -66.05 -65.20   …     -55.36 -54.98 -56.32
F26 -64.87 -64.49 -64.33   …     -54.80 -55.01 -56.92
F27 -63.97 -63.27 -63.33   …     -54.55 -55.34 -57.81
F28 -62.71 -62.26 -62.06   …     -54.59 -55.99 -59.16
F29 -61.64 -61.26 -60.96   …     -54.97 -57.05 -60.88
F30 -60.93 -60.35 -60.19   …     -55.43 -58.37 -62.82
F31 -60.03 -59.37 -59.43   …     -56.19 -59.79 -64.76
F32 -59.11 -58.53 -58.62   …     -57.31 -61.23 -66.56
F33 -58.30 -57.67 -57.79   …     -58.70 -63.05 -68.60
F34 -57.80 -56.89 -57.20   …     -60.24 -65.50 -71.44
F35 -57.42 -56.24 -56.86   …     -61.53 -67.89 -74.75
F36 -56.94 -55.77 -56.65   …     -63.32 -70.14 -77.61
F37 -56.69 -55.63 -56.60   …     -65.92 -73.07 -79.88
F38 -56.67 -55.72 -56.69   …     -68.62 -76.39 -79.07
F39 -56.58 -55.70 -56.72   …     -71.30 -79.54 -76.80
F40 -56.55 -55.55 -56.81   …     -74.26 -83.17 -75.03
F41 -56.89 -55.67 -57.11   …     -77.12 -85.09 -73.43
F42 -57.52 -56.04 -57.47   …     -80.29 -87.09 -71.92
F43 -58.26 -56.73 -58.05   …     -85.37 -86.62 -70.68
F44 -59.10 -57.69 -59.07   …     -91.70 -83.35 -69.50
F45 -60.47 -58.85 -60.52   …     -92.25 -81.10 -68.44
F46 -62.44 -60.31 -62.11   …     -86.14 -80.06 -67.83
F47 -64.36 -62.11 -63.82   …     -83.99 -79.82 -67.78
F48 -66.33 -64.24 -66.10   …     -83.16 -79.51 -68.51
F49 -68.08 -66.65 -68.83   …     -81.42 -79.59 -69.91
F50 -68.54 -68.91 -71.61   …     -79.92 -78.87 -71.48
F51 -69.15 -71.09 -75.12   …     -78.53 -78.05 -73.16
F52 -72.35 -74.64 -79.86   …     -77.95 -78.44 -75.32
F53 -78.57 -80.07 -85.16   …     -77.73 -79.02 -76.51
F54 -86.06 -86.09 -90.41   …     -77.82 -78.91 -77.15
F55 -92.17 -93.58 -98.15   …     -78.16 -78.58 -77.54
F56 -95.49-101.59-100.05   …     -78.48 -78.98 -77.33
F57 -95.83-102.37-101.13   …     -78.59 -79.24 -77.07
```

```
F58 -97.76-109.34          …     -78.03 -79.33 -77.51
F59-101.35-109.38          …     -77.11 -78.68 -78.96
F60 -97.25 -98.23-106.60   …     -76.41 -77.96 -79.56
F61 -85.64 -91.97 -96.80   …     -76.73 -78.26 -79.12
F62 -74.68 -83.22 -89.67   …     -77.84 -79.75 -80.12
F63 -67.85 -76.90 -84.03   …     -79.80 -82.65 -81.75
D00
D01
D02
D03
D04 0.2456 0.2454 0.2452   …     0.2404 0.2402 0.2400
D05 0.2817 0.2814 0.2812   …     0.2750 0.2748 0.2746
D06 0.3185 0.3182 0.3179   …     0.3104 0.3101 0.3098
D07 0.3562 0.3559 0.3555   …     0.3465 0.3462 0.3458
D08 0.3948 0.3944 0.3940   …     0.3835 0.3831 0.3827
D09 0.4343 0.4338 0.4334   …     0.4212 0.4208 0.4203
D10 0.4747 0.4742 0.4737   …     0.4599 0.4594 0.4588
D11 0.5162 0.5156 0.5150   …     0.4995 0.4989 0.4983
D12 0.5587 0.5580 0.5574   …     0.5400 0.5393 0.5386
D13 0.6023 0.6016 0.6008   …     0.5815 0.5808 0.5800
D14 0.6471 0.6463 0.6455   …     0.6241 0.6233 0.6225
D15 0.6931 0.6922 0.6913   …     0.6678 0.6669 0.6660
D16 0.7405 0.7395 0.7385   …     0.7127 0.7117 0.7108
D17 0.7892 0.7881 0.7870   …     0.7589 0.7578 0.7567
D18 0.8394 0.8382 0.8370   …     0.8063 0.8051 0.8040
D19 0.8911 0.8898 0.8886   …     0.8552 0.8539 0.8526
D20 0.9445 0.9431 0.9417   …     0.9055 0.9041 0.9027
D21 0.9997 0.9982 0.9967   …     0.9574 0.9559 0.9544
D22 1.0568 1.0551 1.0535   …     1.0109 1.0093 1.0077
D23 1.1159 1.1141 1.1123   …     1.0662 1.0645 1.0627
D24 1.1771 1.1752 1.1733   …     1.1235 1.1216 1.1197
D25 1.2407 1.2386 1.2365   …     1.1827 1.1807 1.1786
D26 1.3068 1.3046 1.3023   …     1.2442 1.2420 1.2398
D27 1.3757 1.3732 1.3708   …     1.3080 1.3056 1.3032
D28 1.4475 1.4449 1.4422   …     1.3743 1.3718 1.3692
D29 1.5226 1.5197 1.5168   …     1.4434 1.4406 1.4379
D30 1.6012 1.5980 1.5949   …     1.5155 1.5125 1.5095
D31 1.6836 1.6803 1.6769   …     1.5908 1.5876 1.5844
D32 1.7704 1.7668 1.7631   …     1.6697 1.6662 1.6627
D33 1.8620 1.8580 1.8540   …     1.7526 1.7488 1.7450
D34 1.9588 1.9545 1.9501   …     1.8397 1.8356 1.8315
D35 2.0617 2.0569 2.0521   …     1.9317 1.9272 1.9228
D36 2.1713 2.1661 2.1608   …     2.0291 2.0242 2.0193
D37 2.2887 2.2829 2.2771   …     2.1324 2.1271 2.1218
D38 2.4149 2.4085 2.4021   …     2.2427 2.2368 2.2310
D39 2.5515 2.5443 2.5372   …     2.3607 2.3542 2.3478
D40 2.7002 2.6922 2.6842   …     2.4877 2.4806 2.4735
D41 2.8636 2.8546 2.8455   …     2.6253 2.6173 2.6094
D42 3.0448 3.0344 3.0241   …     2.7752 2.7663 2.7574
D43 3.2480 3.2361 3.2242   …     2.9399 2.9298 2.9198
D44 3.4796 3.4655 3.4516   …     3.1227 3.1112 3.0998
D45 3.7485 3.7317 3.7149   …     3.3281 3.3148 3.3016
D46 4.0694 4.0485 4.0279   …     3.5623 3.5467 3.5312
D47 4.4672 4.4402 4.4135   …     3.8350 3.8162 3.7977
D48 4.9907 4.9530 4.9161   …     4.1612 4.1379 4.1149
D49 5.7582 5.6977 5.6392   …     4.5672 4.5369 4.5071
D50                        …     5.1050 5.0624 5.0210
D51                        …                   5.7677
D52
D53
D54
D55
D56
D57
D58
D59
D60
D61
D61
D62
D63
N00
```

```
N01
N02
N03
N04 1.7e+7 1.3e+7 8.3e+6   …     9.3e+7 2.3e+7 1.4e+7
N05 8.9e+6 7.3e+6 4.7e+6   …     3.6e+7 3.3e+6-5.7e+6
N06 5.2e+6 3.8e+6 2.8e+6   …     1.8e+7 1.9e+6-2.7e+6
N07 3.1e+6 2.0e+6 1.9e+6   …     1.1e+7 3.1e+6 1.3e+6
N08 1.8e+6 1.2e+6 1.6e+6   …     5.7e+6 3.0e+6 1.6e+6
N09 1.3e+6 964959 1.3e+6   …     1.9e+6 907918 754334
N10 1.3e+6 768728 923905   …     414979 -20941 465284
N11 1.0e+6 621685 711679   …     443056 9440.2 584411
N12 767281 512404 592273   …     577617 202885 1.1e+6
N13 576843 431121 488397   …     436064 347849 2.0e+6
N14 429862 359385 388558   …     360912 713077 3.8e+6
N15 333126 296551 311766   …     422713 1.5e+6 6.7e+6
N16 304136 257262 258238   …     616336 2.9e+6 1.0e+7
N17 274365 219690 212223   …     868205 4.3e+6 1.3e+7
N18 230314 184889 179919   …     1.1e+6 5.0e+6 1.3e+7
N19 200924 158461 165180   …     1.3e+6 5.1e+6 1.1e+7
N20 177710 146166 157718   …     1.6e+6 4.9e+6 8.7e+6
N21 155008 139360 146398   …     1.7e+6 4.6e+6 6.5e+6
N22 140816 126587 130999   …     1.6e+6 3.8e+6 4.6e+6
N23 121124 109708 120646   …     1.6e+6 2.8e+6 3.0e+6
N24  97263  93412 116639   …     1.6e+6 2.2e+6 1.9e+6
N25  86051  86804 106888   …     1.5e+6 1.6e+6 1.2e+6
N26  77397  85316  89612   …     1.2e+6 1.1e+6 727434
N27  65034  77233  77047   …     851860 718282 412021
N28  59026  66127  70259   …     584131 428478 209074
N29  50985  56198  61063   …     367922 231057  96781
N30  40194  46466  48851   …     225946 116619  42418
N31  32791  38667  38739   …     128777  57111  18438
N32  26779  30998  30818   …      67060  27643 8231.6
N33  21174  24803  24561   …      32615  12167 3448.5
N34  15543  19429  18430   …      15240 4622.4 1196.3
N35  11074  14746  13021   …     7517.4 1769.8 372.01
N36 8063.7  10718 8927.8   …     3299.7 699.22 127.95
N37 5579.9 7232.0 5896.5   …     1201.5 236.46 50.288
N38 3660.6 4631.9 3782.0   …     428.02 73.016 40.260
N39 2451.6 3052.0 2462.6   …     153.45 23.465 45.138
N40 1619.3 2074.6 1583.4   …     51.607 6.7670 45.100
N41 982.38 1326.3 973.26   …     17.781 2.8902 43.531
N42 559.59 801.97 590.94   …     5.7216 1.2082 41.131
N43 311.72 452.26 341.63   …     1.1879 0.9027 36.637
N44 169.68 239.35 178.44   …     0.1858 1.2911 32.235
N45 81.786 121.41 84.666   …     0.1087 1.4566 27.688
N46 34.401 57.447 38.938   …     0.2992 1.2458 21.402
N47 14.599 25.105 17.415   …     0.3312 0.8860 14.571
N48 6.0655 10.083 6.7792   …     0.2702 0.6419 8.2911
N49 2.5061 3.6136 2.2706   …     0.2706 0.4230 4.0321
N50                        …     0.2527 0.3298 1.8604
N51                        …                  0.7945
N52
N53
N54
N55
N56
N57
N58
N59
N60
N61
N62
N63
PIA  0.000  0.028  0.054   …      0.743  0.833  0.939
z    32.52  33.54  32.65   …      33.37  33.36  33.33
Z    32.52  33.56  32.69   …      34.10  34.18  34.25
RR    2.93   3.25   3.09   …      12.16  16.29  20.79
LWC   0.17   0.18   0.17   …       0.76   1.07   1.49
W     6.57   6.73   6.57   …       5.11   4.61   4.16
```

6.4 Raw Spectra

6.4.1 Format Description

Each data block in a **raw spectra** file begins with a header line.

Example:

```
MRR 090612024311 UTC DVS 6.00 DSN 200708021 BW 37300 CC 2079868 MDQ 100 58 58 TYP RAW
```

<	Identifier for MRR data
090612024311	date/time stamp in format YYMMDDhhmmss
UTC	time zone information
DVS␣6.00	Device version number (firmware)
DSN␣200708021	Device serial number
BW␣37300	Bandwidth
CC␣2079868	Calibration constant
MDQ␣100 58 58	Mikro Rain Radar Data quality: percentage of valid spectra, number of valid spectra and number of total spectra
TYP␣RAW	Identifier for data type (raw)

The next data lines contains the measuring heights. It begins with the capital letter H (H means height) and two space characters. The following numbers (9 digits decimal each) represent the measuring heights in meters.

The height line is followed by the line of the transfer function. It starts with the capital characters TF (Transfer Function) and one space character. The rest of that line represents the values of the transfer function for each height step (9 digits decimal each).

The line of the transfer function is followed by 64 data lines. Each one starts with the capital character F and a 2-digit number of the spectra line (0 to 63). The rest of these lines represent the received spectral signal power in engineering units for each height step (9 digits decimal each).

The raw spectra include the receiver noise floor.

6.4.2 Raw Spectra Example

```
MRR 090612024311 UTC DVS 6.00 DSN 0200708021 BW 37300 CC 2079868 MDQ 100 58 58 TYP RAW
H          0       35       70      …         1015     1050     1085
TF  0.003292 0.011523 0.041975      …     0.689026 0.640604 0.422497
F00     4798     2205      166      …            6        6        4
F01     2780     1272      107      …            8        7        5
F02      541      246       33      …           10        8        6
F03       39       22       17      …           11        8        6
F04        4        9       18      …           12        9        6
F05        3        9       19      …           12       11        7
F06        3        9       20      …           13       12        7
F07        3        9       21      …           12       12        7
F08        3       10       23      …           10       11        6
F09        4       11       28      …            9       10        6
F10        5       13       34      …           12        9        5
F11        4       16       44      …           14        8        4
F12        5       18       55      …           13        7        4
F13        7       19       65      …           13        6        5
F14        9       23       84      …           15        9        6
F15       12       34      139      …           17       12        7
F16       15       52      236      …           19       12        8
F17       24       75      325      …           22       12        7
F18       48      120      374      …           23       12        7
F19       98      215      526      …           25       15        9
F20      177      377      803      …           29       19       11
F21      290      582     1054      …           38       24       12
F22      492      873     1270      …           48       31       16
F23      814     1437     1629      …           61       40       22
F24     1103     2015     2193      …           88       55       33
F25     1215     2304     3049      …          130       81       48
F26     1202     2861     4088      …          162      106       61
F27     1692     3945     4978      …          200      124       79
F28     3428     4611     6013      …          282      146       97
F29     6270     5873     8179      …          355      166      105
F30     9754     9622    11394      …          369      204      128
F31    13520    15729    15559      …          331      251      187
F32    15274    23192    21914      …          289      266      227
F33    13520    26471    25550      …          276      245      176
F34     9754    21874    22408      …          273      218      116
F35     6270    15310    16602      …          237      211      110
F36     3428     9683    12461      …          176      178      103
F37     1692     5905    11128      …          119      114       68
F38     1202     4727    11416      …           64       53       32
F39     1215     4582    11578      …           25       21       16
F40     1103     4033    10911      …           15       14       10
F41      814     3225     9611      …           14       13        9
F42      492     2421     7508      …           12       12        8
F43      290     1436     4351      …           12       13        7
F44      177      675     2171      …           13       14        8
F45       98      318     1386      …           14       12        7
F46       48      149      828      …           13       11        7
F47       24       60      332      …           11       11        7
F48       15       21       96      …           10       10        8
F49       12       10       33      …           10        9        7
F50        9        8       19      …           11       10        7
F51        7        7       14      …           11       11        6
F52        5        7       12      …           13       13        7
F53        4        6       11      …           14       13        8
F54        5        8       13      …           14       10        8
F55        4       10       15      …           12        9        6
F56        3        9       15      …           11       10        6
F57        3       10       19      …           11        9        6
F58        3       11       24      …            9        8        6
F59        3       10       24      …           10        8        6
F60        4        9       21      …           10       10        6
F61       39       25       18      …           10       11        6
F62      541      254       29      …           11       10        6
F63     2780     1279       95      …           10        8        4
```

6.5 Removing of the Software

If you want to remove the program from your PC you must be logged in as administrator. If still active you must stop the MRR-Service using the `services` program in the program group `control panel/Administrative Tools`. Then activate the folder `software`, select the entry `METEK MRR Software` and press the button `Add/Remove`. Finally you must manually remove the empty directory (`C:\METEK`) and possibly some data files and directories.

7 Detailed description of the MRR-2 control program

The MRR-2 generates Doppler spectra at 31 height ranges. The data processing is performed by a DSP which is located in the Radar Control and Processing Device (RCPD) at the antenna. The measured data are transmitted by a serial RS-232 port. This port is also used for the device control. If the MRR-2 is connected to a PC, the control, the calculation of further values, and the recording of the data can be done with the MRR-2-control program described below.

The software is divided into two components :

- MRR-Service
- Control Program

The MRR-Service communicates directly with the connected MRR-2, and the Control program performs the operational control of the MRR-2 using the MRR-Service. By means of this the user can interrogate or change the system status in a comfortable way.

Windows® Service Programs

Service programs are software components, which are started automatically when the machine is turned on and the operating system boots. They offer their ‘services’ e.g. control functions and data to other programs. The management of those programs must be provided by the operating system. The starting of a service program needs no manual operation. Only take care that the corresponding service is not deactivated.

Various details of the usage of services depend on the operating system. For this reason the used operating system must be Windows® 2000 or XP. (Windows® Vista and Windows 7 are not supported).

7.1 MRR-Service

The MRR-Service has three functions:

- Communication
- Data recording
- Error handling

7.1.1 Communication

This function of the MRR-Service is needed for the communication between the Control-Program and the MRR-2, for communication a serial interface (RS232 / RS422) is used. With the Control Program the system settings of the MRR-2 can be retrieved and any changes entered by the user are translated to the corresponding commands and transmitted to the MRR-2. (Factory setting of the serial port of the MRR-2 is 57600 baud, 8 bit, no parity, Xon/Xoff handshake protocol.)

7.1.2 Data Recording

The second function of MRR-Service is the recording of the “averaged” or “processed” measured data of the MRR-2. The data is ASCII formatted, so that it is directly readable.

The MRR-Service creates one file each day, whose name is constructed from the actual month, the day (2 characters each) and an additional extension. The boundary between two days is defined as 0:00 (selected time zone including UTC). The file name extension is `.ave` for averaged data and `.pro` for processed data.

All files of a month are stored in a separate directory which will be created automatically if it is not already existing. The names of the directories are constructed from the actual year (4 digits) and the respective month (2 digits).

The path names for the data registration and the port settings may be changed with the MS registry editor regedit.exe at the key

```
HKEY_LOCAL_MACHINE\
   System\
      CurrentControlSet\
         Services\
            MrrSrvc\
               Parameters
```

The variables of this key are shown with their default settings. Change the underlined values, if necessary :

```
Port              REG SZ           COM1
BaudRate          REG DWORD        57600
AveExtension      REG SZ           .ave
AveragedDataFile  REG EXPAND SZ    C:\Metek\ActData\AveData%s
AveragedDataPath  REG EXPAND SZ    C:\Metek\AveData
ProExtension      REG SZ           .pro
ProcessedDataFile REG EXPAND SZ    C:\Metek\ActData\ProcessedData%s
ProcessedDataPath REG EXPAND SZ    C:\Metek\ProcessedData
RawExtension      REG SZ           .raw
RawSpectraFile    REG EXPAND SZ    C:\Metek\ActData\RawSpectra%s
RawSpectraPath    REG EXPAND SZ    C:\Metek\RawSpectra
```

The common root directory is defined by the environmental variable

```
MetekRoot
```

It also can be changed with the registry editor at the following key :

```
HKEY_LOCAL_MACHINE\
   System\
      CurrentControlSet\
         Control\
            Session Manager\
               Environment
```

The variable is :

```
MetekRoot        REG_SZ      C:\METEK
```

The default settings are :

`C:\METEK\ActData`	for actual data(raw, processed and averaged)
`C:\METEK\AveData`	for averaged data
`C:\METEK\ProcessedData`	for processed data
`C:\METEK\RawSpectra`	for raw spectra

The file `C:\METEK\AveData\201101\0106.ave` e.g. would contain the averaged data from January, 6th of 2011.

7.1.3 Error Handling

The third function of the MRR-Service is the recording of all error messages which are caused by the operation of the MRR-2 (except messages which are generated from user input errors).

The error recording is done by the event logging function of the operation system. At the item `application` you find a chronologically sorted list of error messages, which occurred during the operation. Use the Windows event viewer to look at the messages or to store them in other formats. You also can define, how the system shall act if more than the storable number of errors occur. The event viewer is located in the program group `Programs/Administrative Tools.`

7.2 Control Program

The Control Program provides the user access to the MRR-2 through the MRR-Service. The correct installation and the automatic start of the service program are required for a successful start of Control Program. The Control Program allows controlling the MRR-2 also by PCs which are not connected directly to the MRR-2.

It is necessary that there is a network connection to that PC, on which the MRR-Service was started. This network connection may be either a local connection (LAN, Ethernet) or a remote access connection (RAS) which is built up using the Internet or public telephone.

For this remote operation a login at the remote MRR-Service is necessary when you start the program. This ensures that only one user is accessing the MRR-2.

There are no special network installations needed, because no network protocol dependent functions are used between the service and the user interface.

The following picture shows an example for a remote access, where the network connection is performed by a RAS connection. The Control Program on PC #2 uses the network and the MRR-Service on PC #1 to communicate with the MRR-2. The data recording and the event logging is executed on PC #1 which is connected directly to the MRR-2:

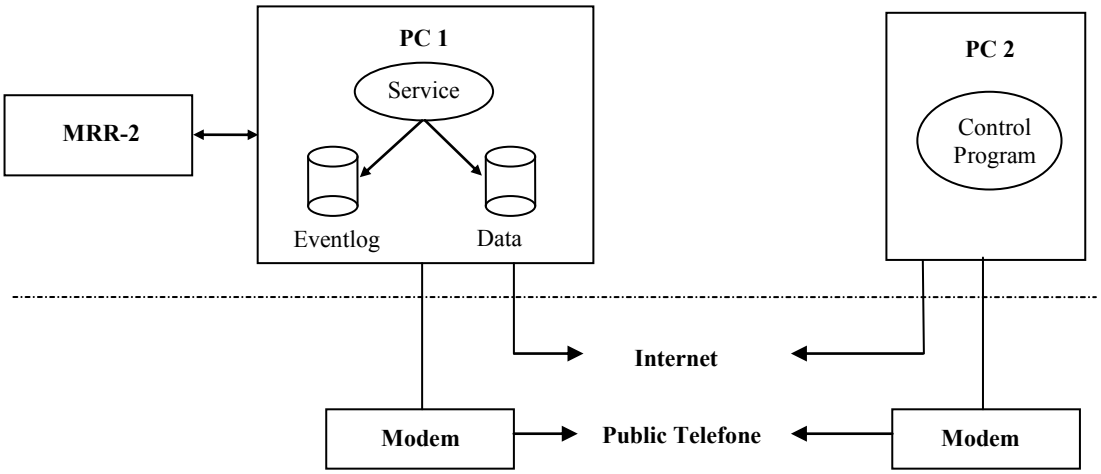


Figure 25: Remote Acces

The software is supplied on a CD-ROM with the following file:

`MRRSetup.exe` the setup program

After installation of the MRR software the port settings may be changed with the MS registry editor regedit.exe at the key

```
HKEY_LOCAL_MACHINE\
   System\
      CurrentControlSet\
         Services\
            MrrSrvc\
               Parameters
```

The port variables of this key are shown with their default settings. Change the underlined values, if necessary :

Port	REG_SZ	COM1
BaudRate	REG_DWORD	**57600**

(You must be logged in with administration rights to change Windows® Registry parameters)

Every time when you change one ore more MRR parameters in the Windows® Registry you have to restart the MRR service because these parameters are only read from the Registry when the service starts.

Open the
`Start/Settings/Control Panel/Administrative Tools/Services`
menu in Windows® 2000. After selecting the MRRService, stop and start it directly with the short cuts or open the **Properties menu** and use the **Stop** and **Start** buttons.

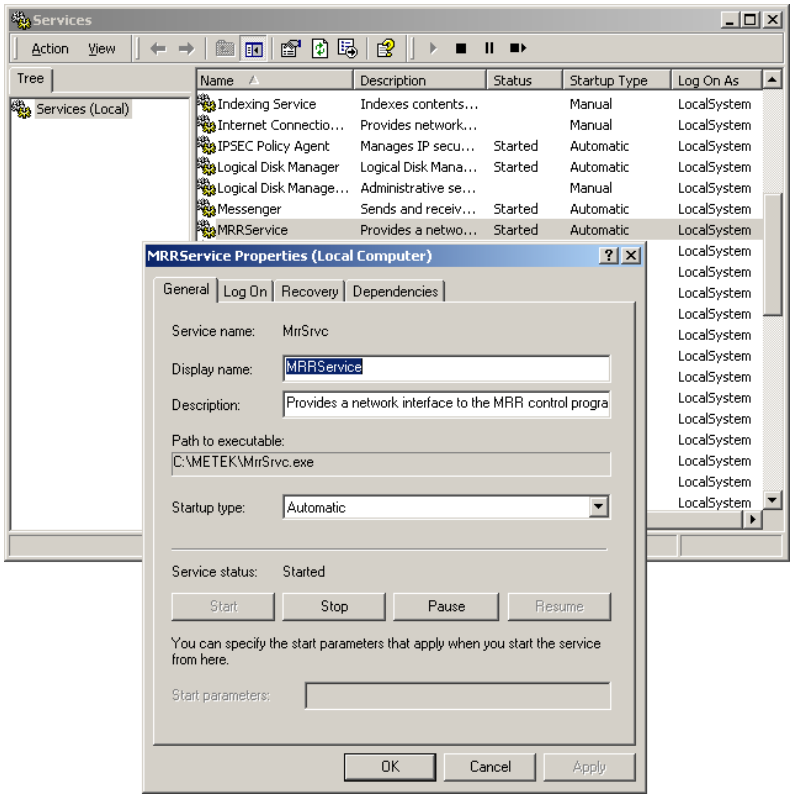


Figure 26: Administrative Tools / Services – Menu (Windows® 2000)

8 MRR-2 Specifications

RCPD with Radar module

Operating Frequency:	24.230 GHz
Operating Mode:	FMCW
Modulation:	1.5 - 15 MHz
Output Power:	50 mW (+17 dBm) (antenna foot point)
OoB and Spurious Emission:	< -80 dBm/MHz (antenna foot point)
2^{nd} Harmonic:	-37 dBm
ITU-Designation:	30M0N0N
Power Supply:	24 VDC / 1A

Antenna

Type:	parabolic offset antenna
Diameter:	600 mm
3 dB Beamwidth:	approx. 1.5 °
Gain:	40.1 dBi

Junction Box / Power Supply:

Input Voltage:	230 VAC (50 .. 60 Hz) or 24 VDC
Output Voltage	24 VAC / 1.5 A
Dimensions:	205 x 145 x 65 mm
Weight:	1.3 Kg

Antenna Heating (Option)

Power Supply:	230 VAC (50 .. 60 Hz)
Power Output:	approx. 200 W

Complete System:

Weight:	17.5 Kg
Dimensions:	800 x 600 x 850 mm

CETECOM ICT Services GmbH

EC Identification number 0682

authorized by the German Government

to act as Notified Body in accordance with the R&TTE Directive 1999/5/EC of 09. March 1999.

CERTIFICATE
EXPERT OPINION

Registration-No.: **E814169R-EO**

Certificate Holder: **METEK**
Meteorologische Meßtechnik GmbH
Fritz-Straßmann-Str. 4

D-25337 Elmshorn

Product Designation: **Mikro-Regen-Radar (MRR) / PreWeS24**

Product Description: **Radar System**

Product Manufacturer: **METEK**
Meteorologische Meßtechnik GmbH
Fritz-Straßmann-Str. 4

D-25337 Elmshorn

Essential requirements	Specifications / Standards	Submitted documents	Result
Radio spectrum (R&TTE, Article 3.2)	EN 300 440-1 V1.3.1 (2001-09) EN 300 440-2 V1.1.1 (2001-09)	Test Report	conform

Marking: **The product shall be signed with CE, our notified body number and the Class II identifier (Alert sign) as shown right hand.**

CE 0682 !

The scope of this evaluation relates to the submitted documents only.
The certificate is only valid in conjunction with the following number of annexes.

Number of annexes: 1

Saarbrücken, 18.10.2004
Place, Date of Issue

Signed by Ernst Hussinger
Notified Body

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